

GAL16V8B GAL16V8A

High Performance E²CMOS PLD

FEATURES

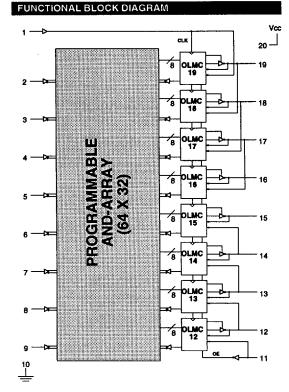
- HIGH PERFORMANCE E2CMOS2 TECHNOLOGY
 - 7.5 ns Maximum Propagation Delay
 - Fmax = 100 MHz
- 5 ns Maximum from Clock Input to Data Output
- TTL Compatible 24 mA Outputs
- UltraMOS® Advanced CMOS Technology
- 50% to 75% REDUCTION IN POWER FROM BIPOLAR
 - 75mA Typ Icc on Low Power Device
- --- 45mA Typ Icc on Quarter Power Device
- ACTIVE PULL-UPS ON ALL PINS (GAL16V8B)
- E2 CELL TECHNOLOGY
- Reconfigurable Logic
- Reprogrammable Cells
- 100% Tested/Guaranteed 100% Yields
- High Speed Electrical Erasure (<100ms)
- 20 Year Data Retention
- EIGHT OUTPUT LOGIC MACROCELLS
 - Maximum Flexibility for Complex Logic Designs
- Programmable Output Polarity
- Also Emulates 20-pin PAL® Devices with Full Function/Fuse Map/Parametric Compatibility
- PRELOAD AND POWER-ON RESET OF ALL REGISTERS
- 100% Functional Testability
- APPLICATIONS INCLUDE:
- DMA Control
- State Machine Control
- High Speed Graphics Processing
- Standard Logic Speed Upgrade
- ELECTRONIC SIGNATURE FOR IDENTIFICATION

DESCRIPTION

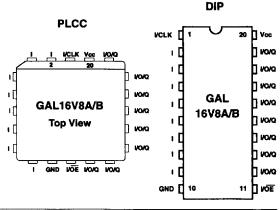
The GAL16V8B, at 7.5 ns maximum propagation delay time, combines a high performance CMOS process with Electrically Erasable (E²) floating gate technology to provide the highest speed performance available in the PLD market. High speed erase times (<100ms) allow the devices to be reprogrammed quickly and efficiently.

The generic architecture provides maximum design flexibility by allowing the Output Logic Macrocell (OLMC) to be configured by the user. An important subset of the many architecture configurations possible with the GAL16V8A/B are the PAL architectures listed in the table of the macrocell description section. GAL16V8A/B devices are capable of emulating any of these PAL architectures with full function/fuse map/parametric compatibility.

Unique test circuitry and reprogrammable cells allow complete AC, DC, and functional testing during manufacture. As a result, LATTICE is able to guarantee 100% field programmability and functionality of all GAL* products. LATTICE also guarantees 100 erase/rewrite cycles and data retention in excess of 20 years.



PIN CONFIGURATION



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LATTICE SEMICONDUCTOR CORP., 5555 N.E. Moore Ct., Hillsboro, Oregon 97124, U.S.A. Tel. (503) 681-0118; 1-800-FASTGAL; FAX (503) 681-3037

May 1992



GAL16V8A/B ORDERING INFORMATION

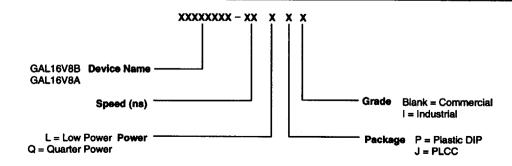
Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	icc (mA)	Ordering #	Package
7.5	7	5	115	GAL16V8B-7LP	20-Pin Plastic DIP
			115	GAL16V8B-7LJ	20-Lead PLCC
10	10	7	115	GAL16V8B-10LP	20-Pin Plastic DIP
	ŀ		115	GAL16V8B-10LJ	20-Lead PLCC
15	12	10	55	GAL16V8A-15QP	20-Pin Plastic DIP
			55	GAL16V8A-15QJ	20-Lead PLCC
			115	GAL16V8A-15LP	20-Pin Plastic DIP
	}		115	GAL16V8A-15LJ	20-Lead PLCC
25	15	12	55	GAL16V8A-25QP	20-Pin Plastic DIP
			55	GAL16V8A-25QJ	20-Lead PLCC
			90	GAL16V8A-25LP	20-Pin Plastic DIP
			90	GAL16V8A-25LJ	20-Lead PLCC

Industrial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
10	10	7	130	GAL16V8B-10LPI	20-Pin Plastic DIP
			130	GAL16V8B-10LJI	20-Lead PLCC
15	12	10	130	GAL16V8B-15LPI	20-Pin Plastic DIP
			130	GAL16V8B-15LJI	20-Lead PLCC
20	13	11	65	GAL16V8A-20QPI	20-Pin Plastic DIP
			65	GAL16V8A-20QJI	20-Lead PLCC
25	15	12	65	GAL16V8A-25QPI	20-Pin Plastic DIP
			65	GAL16V8A-25QJI	20-Lead PLCC
			130	GAL16V8A-25LPI	20-Pin Plastic DIP
			130	GAL16V8A-25LJI	20-Lead PLCC

PART NUMBER DESCRIPTION





OUTPUT LOGIC MACROCELL (OLMC)

The following discussion pertains to configuring the output logic macrocell. It should be noted that actual implementation is accomplished by development software/hardware and is completely transparent to the user.

There are three global OLMC configuration modes possible: simple, complex, and registered. Details of each of these modes are illustrated in the following pages. Two global bits, SYN and ACO, control the mode configuration for all macrocells. The XOR bit of each macrocell controls the polarity of the output in any of the three modes, while the AC1 bit of each of the macrocells controls the input/output configuration. These two global and 16 individual architecture bits define all possible configurations in a GAL16V8A/B. The information given on these architecture bits is only to give a better understanding of the device. Compiler software will transparently set these architecture bits from the pin definitions, so the user should not need to directly manipulate these architecture bits.

The following is a list of the PAL architectures that the GAL16V8A and GAL16V8B can emulate. It also shows the OLMC mode under which the GAL16V8A/B emulates the PAL architecture.

PAL Architectures	GAL16V8A/B
Emulated by GAL16V8A/B	Global OLMC Mode
16R8	Registered
16R6	Registered
16R4	Registered
16RP8	Registered
16RP6	Registered
16RP4	Registered
	-
16L8	Complex
16H8	Complex
16P8	Complex
10L8	Simple
12L6	Simple
14L4	Simple
16L2	Simple
10H8	Simple
12H6	Simple
14H4	Simple
16H2	Simple
10P8	Simple
12P6	Simple
14P4	Simple
16P2	Simple

COMPILER SUPPORT FOR OLMC

Software compilers support the three different global OLMC modes as different device types. These device types are listed in the table below. Most compilers have the ability to automatically select the device type, generally based on the register usage and output enable (OE) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with OE controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without OE control. The different device types listed in the table can be used to override the automatic device selection by the software. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode.

In registered mode pin 1 and pin 11 are permanently configured as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In complex mode pin 1 and pin 11 become dedicated inputs and use the feedback paths of pin 19 and pin 12 respectively. Because of this feedback path usage, pin 19 and pin 12 do not have the feedback option in this mode.

In simple mode all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins (pins 15 and 16) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

	Registered	Complex	Simple	Auto Mode Select
ABEL	P16V8R	P16V8C	P16V8AS	P16V8
CUPL	G16V8MS	G16V8MA	G16V8AS	G16V8
LOGAC	GAL16V8_R	GAL16V8_C7	GAL16V8_C8	GAL16V8
OrCAD-PLD	"Registered" ¹	"Complex" ¹	"Simple"1	GAL16V8A
PLDesigner	P16V8R2	P16V8C ²	P16V8C ²	P16V8A
TANGO-PLD	G16V8R	G16V8C	G16V8AS3	G16V8

- 1) Used with Configuration keyword.
- 2) Prior to Version 2.0 support.
- 3) Supported on Version 1.20 or later.

Specifications **GAL16V8B GAL16V8A**

REGISTERED MODE

In the Registered mode, macrocells are configured as dedicated registered outputs or as I/O functions.

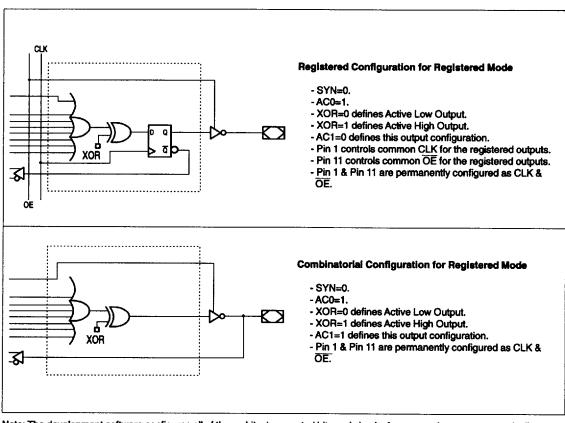
Architecture configurations available in this mode are similar to the common 16R8 and 16RP4 devices with various permutations of polarity, I/O and register placement.

All registered macrocells share common clock and output enable control pins. Any macrocell can be configured as registered or I/O. Up to eight registers or up to eight I/O's are possible in this

mode. Dedicated input or output functions can be implemented as subsets of the I/O function.

Registered outputs have eight product terms per output. I/O's have seven product terms per output.

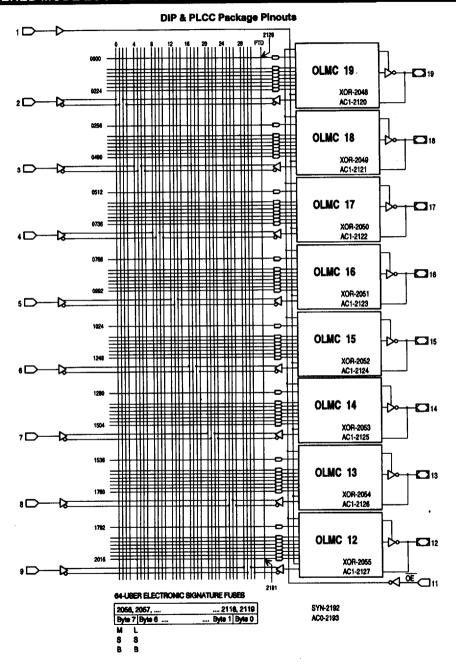
The JEDEC fuse numbers, including the User Electronic Signature (UES) fuses and the Product Term Disable (PTD) fuses, are shown on the logic diagram on the following page.



Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



REGISTERED MODE LOGIC DIAGRAM





Specifications **GAL16V8B GAL16V8A**

COMPLEX MODE

In the Complex mode, macrocells are configured as output only or I/O functions.

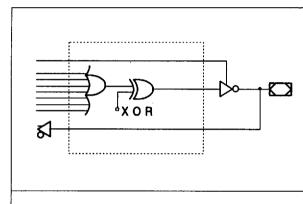
Architecture configurations available in this mode are similar to the common 16L8 and 16P8 devices with programmable polarity in each macrocell.

Up to six I/O's are possible in this mode. Dedicated inputs or outputs can be implemented as subsets of the I/O function. The two outer most macrocells (pins 12 & 19) do not have input ca-

pability. Designs requiring eight I/O's can be implemented in the Registered mode.

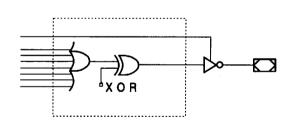
All macrocells have seven product terms per output. One product term is used for programmable output enable control. Pins 1 and 11 are always available as data inputs into the AND array.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.



Combinatorial I/O Configuration for Complex Mode

- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1.
- Pin 13 through Pin 18 are configured to this function.



Combinatorial Output Configuration for Complex Mode

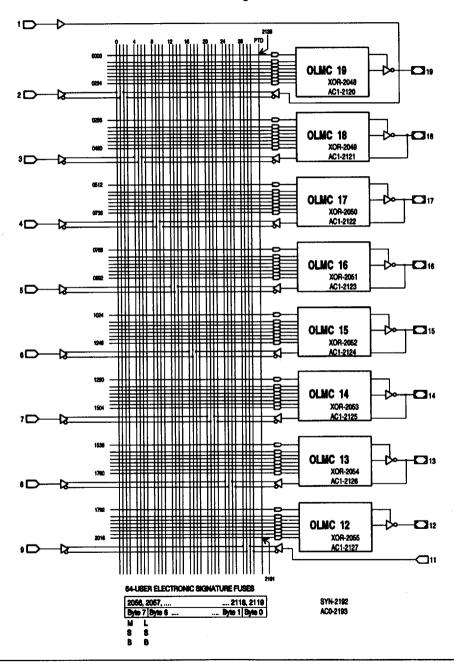
- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1
- Pin 12 and Pin 19 are configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



COMPLEX MODE LOGIC DIAGRAM

DIP & PLCC Package Pinouts





Specifications **GAL16V8B GAL16V8A**

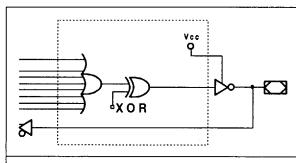
SIMPLE MODE

In the Simple mode, macrocells are configured as dedicated inputs or as dedicated, always active, combinatorial outputs.

Architecture configurations available in this mode are similar to the common 10L8 and 12P6 devices with many permutations of generic output polarity or input choices.

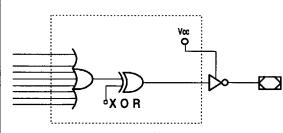
All outputs in the simple mode have a maximum of eight product terms that can control the logic. In addition, each output has programmable polarity. Pins 1 and 11 are always available as data inputs into the AND array. The center two macrocells (pins 15 & 16) cannot be used as input or I/O pins, and are only available as dedicated outputs.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram.



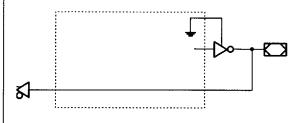
Combinatorial Output with Feedback Configuration for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- All OLMC except pins 15 & 16 can be configured to this function.



Combinatorial Output Configuration for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- Pins 15 & 16 are permanently configured to this function.



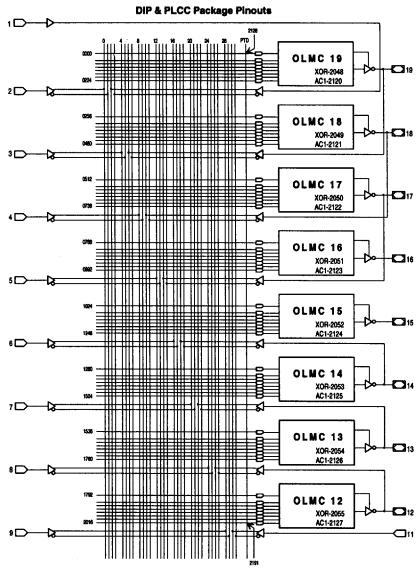
Dedicated Input Configuration for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1 defines this configuration.
- All OLMC except pins 15 & 16 can be configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



SIMPLE MODE LOGIC DIAGRAM



64-USER	FI FCT	RONIC:	SIGNAT	LIRE E	IRFR
OT COLIN	LL DUI			UNER	V0-4

2066, 2067,		2118, 2119
B ₂ 1	♦ 7 Byte 6	Byte 1 Byte 0
M	L	
8	8	
R	R	

SYN-2192 AC0-2193



Specifications **GAL16V8B**Commercial

ABSOLUTE MAXIMUM RATINGS(1)

Supply voltage V _{cc}	0.5 to +7V
Input voltage applied	
Off-state output voltage applied	2.5 to V _{cc} +1.0V
Storage Temperature	
Ambient Temperature with	
Dewer Applied	_55 to 125°C

Power Applied-55 to 125°C
Stresses above those listed under the "Absolute Maximum

1.Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Commercial Devices:

Ambient Temperature (T _A)	0 to 75°C
Supply voltage (V _{cc})	
with Respect to Ground+4.75 t	o +5.25V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.3	MAX.	UNITS
VIL	Input Low Voltage		Vss - 0.5	_	0.8	٧
ViH	Input High Voltage		2.0	_	Vcc+1	٧
he	Input or I/O Low Leakage Current	0V ≤ Vin ≤ ViL (MAX.)		_	-100	μА
Iн	Input or I/O High Leakage Current	3.5V ≤ V in ≤ V cc		-	10	μА
V OL	Output Low Voltage	IoL = MAX. Vin = VIL or VIH			0.5	٧
V OH	Output High Voltage	ion = MAX. Vin = VIL or VIH	2.4	_	_	٧
I OL	Low Level Output Current		_	_	24	mA
Юн	High Level Output Current		_	_	-3.2	mA
los²	Output Short Circuit Current	Vcc = 5V Vouτ = 0.5V T _A = 25°C	-30		150	mA
Icc	Operating Power Supply Current	V _{IL} = 0.5V V _{IH} = 3.0V floogle = 25MHz Outputs Open (no load)	_	75	115	mA

¹⁾ The leakage current is due to the internal pull-up resistor on all pins. See Input Buffer section for more information.

CAPACITANCE ($T_a = 25 \text{ C}, f = 1.0 \text{ MHz}$)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C,	Input Capacitance	8	pF	$V_{\infty} = 5.0V, V_{i} = 2.0V$
C _{vo}	I/O Capacitance	8	pF	$V_{cc} = 5.0V, V_{yo} = 2.0V$

^{*}Guaranteed but not 100% tested.

One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Guaranteed but not 100% tested.

³⁾ Typical values are at Vcc = 5V and TA = 25 °C



Specifications GAL16V8B **Commercial**

AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

	TEST	ST DESCRIPTION			7	-10		
PARAMETER	COND1.	COND'.		MIN.	MAX.	MIN.	MAX.	UNITS
t pd	1	Input or I/O to Combinational Output	8 outputs switching	3	7.5	3	10	ns
			1 output switching	_	7		_	ns
t co	1	Clock to Output Delay		2	5	2	7	ns
tcf²	_	Clock to Feedback Delay		_	3		6	ns
t su	_	Setup Time, Input or Feedback before Clo	ock	7		10	_	ns
t h	_	Hold Time, Input or Feedback after Clock			_	0		ns
	1	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)		83.3	_	58.8		MHz
fmax ³	1	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)			_	62.5	_	MHz
	1	Maximum Clock Frequency with No Feedback				62.5	_	MHz
twh	_	Clock Pulse Duration, High		5	_	8	_	ns
twi	_	Clock Pulse Duration, Low			_	8	_	ns
ten	2	Input or I/O to Output Enabled		3	9	3	10	ns
	2	OE to Output Enabled			6	2	10	ns
tdis	3	Input or I/O to Output Disabled			9	2	10	ns
	3	OE to Output Disabled		1.5	6	1.5	10	ns

- 1) Refer to Switching Test Conditions section.
- 2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.
- 3) Refer to fmax Descriptions section.

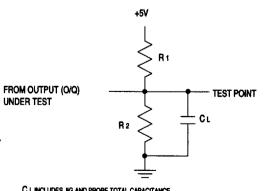
SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	3ns 10% - 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active level.

Output Load Conditions (see figure)

Test Condition		Test Condition R1		CL
1		200Ω	390Ω	50pF
2	Active High	∞	390Ω	50pF
	Active Low	200Ω	390Ω	50pF
3	Active High	00	390Ω	5pF
	Active Low	200Ω	390Ω	5pF



C L INCLUDES JIG AND PROBE TOTAL CAPACITANCE



Specifications **GAL16V8A**Commercial

ABSOLUTE MAXIMUM RATINGS(1)

Supply voltage V _{cc}	•	0.5 to +7V
Input voltage applied		
Off-state output voltage applied		
Storage Temperature		
Ambient Temperature with		
Power Applied		55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Commercial Devices:

Ambient Temperature (T _A)	0 to 75°C
Supply voltage (V _{cc})	
with Respect to Ground+4.7	'5 to +5.25V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	PARAMETER CONDITION		MIN.	TYP.2	MAX.	UNITS		
VIL	Input Low Voltage					Vss - 0.5		0.8	V
Vін	Input High Voltage					2.0	_	Vcc+1	V
lı.	Input or I/O Low Leakage Current		0V ≤ \	IN ≤ VIL (MAX.)			_	-10	μА
ЫН	Input or I/O High Leakage Current		Vin≤\	√in ≤ Vcc			_ ,	10	μА
V OL	Output Low Voltage	put Low Voltage		loL = MAX. Vin = VIL or VIH		_	0.5	V	
V OH	Output High Voltage	юн = MAX. N		MAX. Vin = VIL or	Viн	2.4	_	-	V
l OL	Low Level Output Cu	Current			_	_	24	mA	
Юн	High Level Output C	urrent				_	_	-3.2	mA
los ¹	Output Short Circuit	Current	V∞ = 5V Voυτ = 0.5V T _A = 25°C		-30	_	-150	mA	
Icc	Operating Power	VIL = 0.5V VIH :	V _{IH} = 3.0V floggle = 25MHz L -15		_	75	115	mA	
	Supply Current	Outputs Open (r	ts Open (no load) 1000 = 15MHz L -25		_	75	90	mA	
				floggie = 15MHz	Q -15/-25	–	45	55	mA

¹⁾ One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Guaranteed but not 100% tested.

CAPACITANCE (T_a = 25 C, f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C _I	Input Capacitance	8	pF	$V_{\infty} = 5.0V, V_{I} = 2.0V$
C _{vo}	I/O Capacitance	10	pF	$V_{cc} = 5.0V, V_{vo} = 2.0V$

^{*}Guaranteed but not 100% tested.

²⁾ Typical values are at Vcc = 5V and TA = 25 °C



Specifications GAL16V8A **Commercial**

AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

	TEST	DESCRIPTION	-1	15	-25		
PARAMETER	COND'.	DECOMP HOW	MIN.	MAX.	MIN.	MAX.	UNITS
t pd	1	Input or I/O to Combinational Output	3	15	3	25	ns
t co	1	Clock to Output Delay	2	10	2	12	ns
t cf ²	-	Clock to Feedback Delay		8	_	10	ns
t su		Setup Time, Input or Feedback before Clock	12		15		ns
th	_	Hold Time, Input or Feedback after Clock	0	_	0		ns
	1 Maximum Clock Frequency with External Feedback, 1/(tsu + tco)		45.5	_	37	_	MHz
fmax ³	1	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	50	_	40	-	MHz
•	Maximum Clock Frequency with No Feedback		62.5	_	41.6	-	MHz
twh	-	Clock Pulse Duration, High	8	_	12	_	ns
twi	_	Clock Pulse Duration, Low	8	-	12	 	ns
ten	n 2 Input or I/O to Output Enabled		1 –	15	_	25	ns
	2	OE to Output Enabled		15	_	20	ns
t dis	tdis 3 Input or I/O to Output Disabled			15		25	ns
	3	OE to Output Disabled		15	_	20	ns

- 1) Refer to Switching Test Conditions section.
- 2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.
- 3) Refer to fmax Descriptions section.

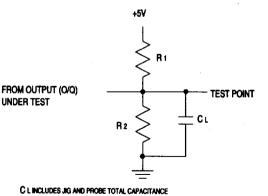
SWITCHING TEST CONDITIONS

Input Puise Levels	GND to 3.0V
Input Rise and Fall Times	3ns 10% - 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active

Output Load Conditions (see figure)

Tes	t Condition	Rı	R ₂	CL
1		200Ω	390Ω	50pF
2	Active High	80	390Ω	50pF
	Active Low	200Ω	390Ω	50pF
3	Active High	∞	390Ω	5pF
	Active Low	200Ω	390Ω	5pF





Specifications **GAL16V8B**Industrial

ABSOLUTE MAXIMUM RATINGS(1)

Supply voltage V _{cc}	0.5 to +7V
Input voltage applied	
Off-state output voltage applied .	2.5 to V _{cc} +1.0V
Storage Temperature	65 to 150°C
Ambient Temperature with	

Power Applied55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Industrial Devices:

Ambient Temperature (T ₄)	40 to 85°C
Supply voltage (V _{cc})	
with Respect to Ground	+4.50 to +5.50V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.	MAX.	UNITS
VIL	Input Low Voltage		Vss - 0.5	_	0.8	V
V IH	Input High Voltage		2.0	_	Vcc+1	٧
hi:	Input or I/O Low Leakage Current	0V ≤ Vin ≤ Vil (MAX.)			-100	μА
lін	Input or I/O High Leakage Current	3.5V ≤ Vin ≤ Vcc	_	_	10	μА
V OL	Output Low Voltage	IoL = MAX. Vin = VIL or VIH	_		0.5	V
V OH	Output High Voltage	IOH = MAX. Vin = VIL OF VIH	2.4	_	_	V
loL	Low Level Output Current		_	_	24	mA
Юн	High Level Output Current		_	_	-3.2	mA
los²	Output Short Circuit Current	Vcc = 5V Vouτ = 0.5V T _A = 25°C	-30	_	-150	mA
Icc	Operating Power Supply Current	V _{IL} = 0.5V V _{IH} = 3.0V ftoggle = 25MHz Outputs Open (no load)	_	75	130	mA

¹⁾ The leakage current is due to the internal pull-up on all pins. See Input Buffer section for more information.

CAPACITANCE (T, = 25 C, f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
Cı	Input Capacitance	8	pF	$V_{cc} = 5.0V, V_{i} = 2.0V$
C ^{no}	I/O Capacitance	8	pF	$V_{cc} = 5.0V, V_{vo} = 2.0V$

^{*}Guaranteed but not 100% tested.

One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Guaranteed but not 100% tested.

³⁾ Typical values are at Vcc = 5V and TA = 25 °C



AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

PARAMETER	TEST	DESCRIPTION	-1	10	-1	15	
PAKAMETEK	COND1.	DESCRIPTION		MAX.	MIN.	MAX.	UNITS
t pd	1	Input or I/O to Combinational Output		10	3	15	ns
tco	1	Clock to Output Delay	2	7	2	10	ns
t cf²	_	Clock to Feedback Delay	-	6		8	ns
t su	-	Setup Time, Input or Feedback before Clock	10		12	_	ns
t h	_	Hold Time, Input or Feedback after Clock	0	_	0	 	ns
	1	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)	58.8	_	45.5	_	MHz
fmax ³	1	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	62.5	_	50	-	MHz
	1	Maximum Clock Frequency with No Feedback	62.5	_	62.5	_	MHz
t wh		Clock Pulse Duration, High	8	_	8	_	ns
twi		Clock Pulse Duration, Low	8	_	8	_	ns
ten	2	Input or I/O to Output Enabled	3	10		15	ns
	2 OE to Output Enabled		2	10	_	15	ns
t dis	3	Input or I/O to Output Disabled	2	10	_	15	ns
	3	OE to Output Disabled	1.5	10	_	15	ns

- 1) Refer to Switching Test Conditions section.
- 2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.
- 3) Refer to fmax Descriptions section.

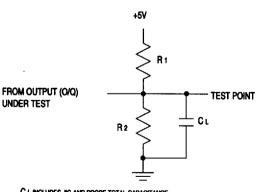
SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	3ns 10% - 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active level.

Output Load Conditions (see figure)

Test Condition		R ₁	R ₂	CL
		200Ω	390Ω	50pF
2	Active High	ee	390Ω	50pF
	Active Low	200Ω	390Ω	50pF
3	Active High	∞	390Ω	5pF
	Active Low	200Ω	390Ω	5pF



C L INCLUDES JIG AND PROBE TOTAL CAPACITANCE



Specifications **GAL16V8A**Industrial

ABSOLUTE MAXIMUM RATINGS(1)

Supply voltage V _{cc}	0.5 to +7V
Input voltage applied	
Off-state output voltage applied	
Storage Temperature	65 to 150°C
Ambient Temperature with	
Power Applied	55 to 125°C

1.Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Industrial Devices:

Ambient Temperature (T _A)	40 to 85°C
Supply voltage (V _{cc})	
with Respect to Ground	+4.50 to +5.50V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER		CONDITION		MIN.	TYP.2	MAX.	UNITS	
VIL	Input Low Voltage					Vss - 0.5		0.8	V
ViH	Input High Voltage					2.0	_	Vcc+1	٧
lı.	Input or I/O Low Lea	kage Current	0V ≤ \	VIN ≤ VIL (MAX.)		_	1	-10	μА
lін	Input or I/O High Leakage Current		V ıн ≤ \	Vin ≤ Vcc			_	10	μА
V OL	Output Low Voltage		lou = N	MAX. Vin = VIL or	V iH	_	-	0.5	V
V OH	Output High Voltage		юн = 1	MAX. Vin = VIL or	ViH	2.4	_	_	v
loL	Low Level Output C	urrent				_		24	mA
ЮН	High Level Output C	urrent				_	_	-3.2	mA
los ¹	Output Short Circuit	Current	Vcc =	5V V ουτ = 0.5V	T _A = 25°C	-30		-150	mA
lcc	Operating Power	VIL = 0.5V VIH :	= 3.0V	ftoggie = 25MHz	L -25		75	130	mA
	Supply Current	Outputs Open (n	o load)	froggle = 15MHz	Q -20/-25	_	45	65	mA

¹⁾ One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Guaranteed but not 100% tested.

CAPACITANCE ($T_A = 25$ C, f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C,	Input Capacitance	8	pF	$V_{cc} = 5.0V, V_i = 2.0V$
C _{vo}	I/O Capacitance	10	pF	$V_{cc} = 5.0V, V_{vo} = 2.0V$

^{*}Guaranteed but not 100% tested.

²⁾ Typical values are at Vcc = 5V and TA = 25 °C



Specifications GAL16V8A Industrial

AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

PARAMETER	TEST	DESCRIPTION	-2	20	-25		
PAKAMEIEH	COND1.	DESCRIPTION	MIN. MAX.		MIN.	MAX.	UNITS
t pd	1	Input or I/O to Combinational Output	3	20	3	25	ns
tco	1	Clock to Output Delay	2	11	2	12	ns
tc#	_	Clock to Feedback Delay	_	9	_	10	ns
t su		Setup Time, input or Feedback before Clock	13	_	15		ns
th	_	Hold Time, Input or Feedback after Clock	0	_	0		ns
	1	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)	41.6	_	37	_	MHz
fmax ³	1	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	45.4	_	40	_	MHz
	1	Maximum Clock Frequency with No Feedback	50	_	41.6		MHz
twh	_	Clock Pulse Duration, High	10	_	12	_	ns
twi	.—	Clock Pulse Duration, Low	10	_	12	_	ns
t en	ten 2 input or I/O to Output		_	20	_	25	ns
	2 OE to Output			18	_	20	ns
t dis	3	Input or I/O to Output	_	20	_	25	ns
	3	ŌĒ to Output	_	18	_	20	ns

- 1) Refer to Switching Test Conditions section.
- 2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.
- 3) Refer to fmax Descriptions section.

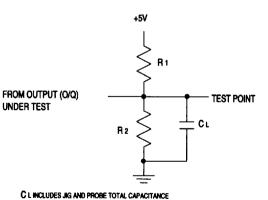
SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	3ns 10% - 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active level.

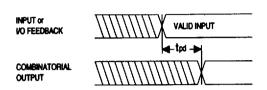
Output Load Conditions (see figure)

Tes	t Condition	R ₁	R ₂	CL
1	200Ω		390Ω	50pF
2	Active High	∞	390Ω	50pF
	Active Low	200Ω	390Ω	50pF
3	Active High	•	390Ω	5pF
	Active Low	200Ω	390Ω	5pF

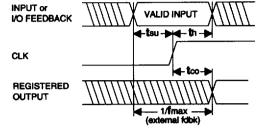




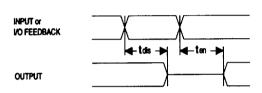
SWITCHING WAVEFORMS



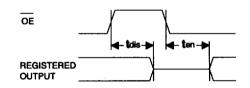
Combinatorial Output



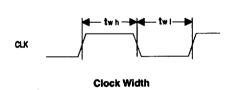
Registered Output

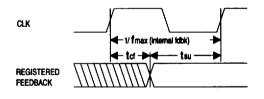


Input or I/O to Output Enable/Disable



OE to Output Enable/Disable

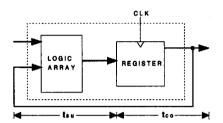




fmax with Feedback

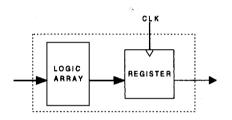


fmax DESCRIPTIONS



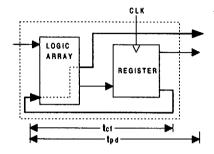
fmax with External Feedback 1/(tsu+tco)

Note: fmax with external feedback is calculated from measured tsu and tco.



fmax With No Feedback

Note: fmax with no feedback may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.



fmax with Internal Feedback 1/(tsu+tcf)

Note: tcf is a calculated value, derived by subtracting tsu from the period of fmax w/internal feedback (tcf = 1/fmax - tsu). The value of tcf is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to tcf + tpd.



Specifications **GAL16V8B GAL16V8A**

ELECTRONIC SIGNATURE

An electronic signature is provided in every GAL16V8A/B device. It contains 64 bits of reprogrammable memory that can contain user defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

NOTE: The electronic signature is included in checksum calculations. Changing the electronic signature will alter checksum.

SECURITY CELL

A security cell is provided in the GAL16V8A/B devices to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

LATCH-UP PROTECTION

GAL16V8A/B devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias is of sufficient magnitude to prevent input undershoots from causing the circuitry to latch. Additionally, outputs are designed with n-channel pull-ups instead of the traditional p-channel pull-ups to eliminate any possibility of SCR induced latching.

DEVICE PROGRAMMING

GAL devices are programmed using a Lattice-approved Logic Programmer, available from a number of manufacturers (see the GAL Development Tools section). Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.

OUTPUT REGISTER PRELOAD

When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because, in system operation, certain events occur that may throw the logic into an illegal state (power-up, line voltage gitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

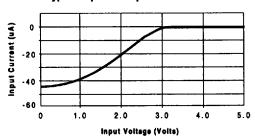
GAL16V8A/B devices include circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing text vectors perform output register preload automatically.

INPUT BUFFERS

GAL16V8A/B devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

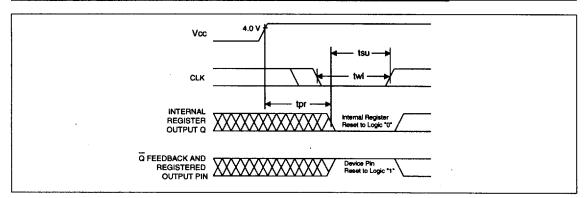
The GAL16V8B input and I/O pins have built-in active pull-ups. As a result, unused inputs and I/O's will float to a TTL "high" (logical "1"). In contrast, the GAL16V8A does not have active pull-ups within their input structures. Lattice recommends that all unused inputs and tri-stated I/O pins for both devices be connected to another active input, V_{DC}, or Ground. Doing this will tend to improve noise immunity and reduce I_{DC} for the device.

Typical Input Pull-up Characteristic



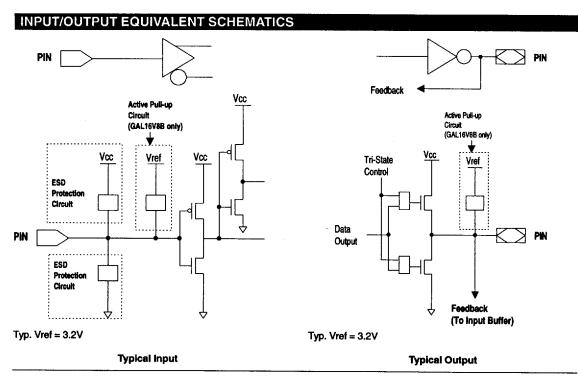


POWER-UP RESET



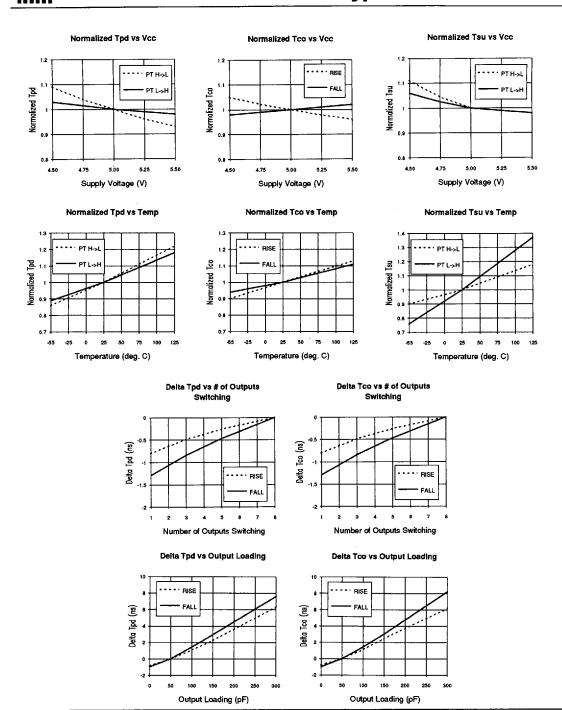
Circuitry within the GAL16V8A/B provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time (tpr, 1µs MAX). As a result, the state on the registered output pins (if they are enabled) will always be high on power-up, regardless of the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. Because of the asynchronous nature of system power-up, some

conditions must be met to guarantee a valid power-up reset of the device. First, the Vcc rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of tpr time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.



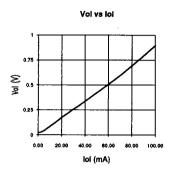


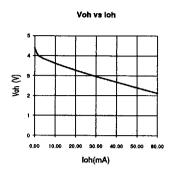
Specifications *GAL16V8B*Typical Characteristics

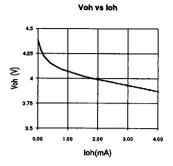


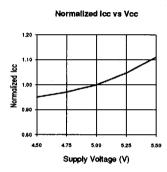


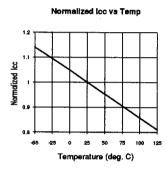
Specifications *GAL16V8B* **Typical Characteristics**

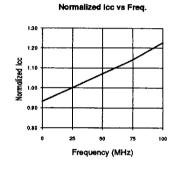


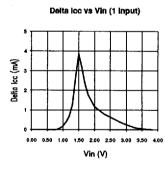


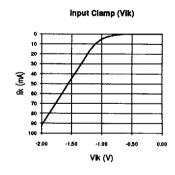














Specifications *GAL16V8A*Typical Characteristics

